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Page 42 The form closure grip is the second principle for gripping objects.

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The Three Laws of Robotics (often shortened to The Three Laws or known as Asimov's Laws) are a set of rules devised by the science fiction author Isaac Asimov. The rules were introduced in his 1942 short story "Runaround" (included in the 1950 collection I, Robot), although they had been foreshadowed in a few earlier stories. The Three Laws, quoted as being from the "Handbook of Robotics, 56th ...

Three Laws of Robotics - Wikipedia

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