

discrete sliding mode control pdf

In control systems, sliding mode control (SMC) is a nonlinear control method that alters the dynamics of a nonlinear system by application of a discontinuous control signal (or more rigorously, a set-valued control signal) that forces the system to "slide" along a cross-section of the system's normal behavior. The state-feedback control law is not a continuous function of time.

Sliding mode control - Wikipedia

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Fundamentally, there are two types of control loops: open loop control and closed loop (feedback) control. Control theory is concerned only with closed loop control.

Control theory - Wikipedia

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International Journal of Control: Vol 91, No 7

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Sam's Laser FAQ - Home-Built Diode Pumped Solid State

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